



Motor Acceleration Time Report for NEP MV Motors

for

NEP Canada Inc

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Prepared for:

Mr. Jeff Hogan P.Eng.

of

MAC Engineering

Prepared by:

Malcolm Steeves P.Eng.

Ref #: ES03383





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Results Summary:

Two motors were tested:

Toshiba 2500 hp 1182RPM
Frame 590-1400
4160 / 3 / 60 Volts 331 Amps FLC
Class F rise, Class H Insulation, Code F
Type TIKE SF 1.0
SN 060011007BH

IEM 1250 hp 1191 RPM
Frame 6808
4160 / 3 / 60 Volts, 155 Amps FLC
Code C
Type HWPI, SF 1.15
SN 8904001

An acceptable acceleration time for the **Toshiba 2500 hp motor is 38 seconds** and for the **IEM 1250 hp, it is 34 seconds**.





Process:

The design of an electric motor by North American NEMA standard specifies certain performance requirements in Standard MG1.

Specifically the motor must be able to run at full load current at design voltage and deliver nameplate horsepower without exceeding the temperature rise listed on the nameplate, or insulation class rise if there is no listing on the nameplate.

Further, the motor must be able to accelerate the inertia of the motor rotor, the coupling and load inertia without exceeding the temperature rise limits.

Using the procedure from IEEE Standard 112 Clause 7.3.2 Method 2, measuring the current, voltage rotational speed and time, the power, power factor, torque and rotor moment of inertia are calculated.

$$S = 3V_{\phi}I_{\phi}$$
$$P = S \cos(\theta)$$
$$\% = P / \text{VA}$$
$$J_M = - \frac{P}{\omega} \times 100\%$$

Where

S is the summed product of the phase voltage and the phase current expressed in VA

V_φ is the phase voltage or $V_{LL} \sqrt{3}$ if the voltage measured is V_{LL} and is expressed in Volts

I_φ is the measured phase current expressed in Amps

P is the power expressed in Watts

cos(θ) is the power factor or cosine of the angle (θ) between the phase current and phase voltage

T is torque expressed in N-m

ω is the angular velocity expressed in radians/second

J_M is the moment of inertia for the motor rotor expressed in kgm²

Δt is a time difference expressed in seconds

Using these results and adding the design limits specified in NEMA MG1, we can then identify the acceleration time for the total moment of inertia. The temperature rise was then checked to be sure it remains within limits for at least two starts, another requirement of NEMA MG1.

The motor was started at reduced voltage after measuring the cold winding resistance and inductance. The temperature rise was measured and recorded. The three phase voltages, the three phase currents and the rotational velocity were measured and



recorded. The calculations were done according to the preceding formulae and the results recorded. The reduced voltage start was done due to limitations of the starting equipment and to ensure worst case starting conditions.

After the measurements had been taken the motor was shut down and allowed to coast to a stop. The final winding temperature was checked and recorded.

Another start was done and the winding temperature was recorded immediately before the start and upon completion of the start. The voltage was raised to nameplate voltage and held there for the remainder of the test. The losses due to friction, windage, i^2R losses and core losses are measured and the motor was allowed to run with only the losses until the temperature stabilized. The temperature difference between the stabilized temperature and ambient represents the temperature rise from the motors watts lost. This temperature difference is affected by the relative humidity and ambient temperature.

The thermal capacity of the electric motor can be expressed as the energy required to raise the temperature of the motor mass per unit of temperature, or expressed mathematically as

$$C_{TM} = P \times dt/dT$$

or

$$C_{TM} = P \times \Delta t / \Delta T$$

where

C_{TM} is the thermal capacity of the motor

P is the power used by the motor to make heat expressed in watts

Δt is the time difference to reach temperature stability from starting temperature to stabilized temperature expressed in seconds

ΔT is the temperature difference between the starting temperature and the final stabilized temperature expressed in °C

The total thermal energy that the motor can absorb for in this case Class H insulation is calculated using C_{TM} and the rise for Class H insulation (185°C).

The energy required to accelerate the motor rotor and the NEMA MG1 design load inertia can then be calculated.

$$E = (((J_M + J_L) \times \Delta \omega / \Delta t_a) \times (V_{\theta R} / V_{\theta T})^2 \times \Delta \omega) \times \Delta t_a$$

where

E is energy expressed in Watt seconds

J_M is the moment of inertia for the motor rotor expressed in Kg-m²

J_L is the moment of inertia for the load





- $\Delta\omega$ is the change in rotational velocity expressed as radians/sec
 Δt_a is the acceleration time for the designed inertia
 $V_{\theta R}$ is the rated voltage for the motor expressed in Volts
 $V_{\theta T}$ is the test voltage used when the motor was tested expressed in volts

This was expressed as percent of the available thermal capacity.





Continental Group Edmonton

Continental Electrical Motor Services (Northern) Ltd.

Details:



#201 4015 8th St. SE, Calgary, Alberta, T2G 3A5
Ph: (403) 236-9428 Fax: (403) 279-6782
Email: cems@continental-electric.com



8909 15th St. NW, Edmonton, Alberta, T6P 0B8
Ph: (780) 410-8800 Fax: (780) 410-1663
Email: cemsn@continental-electric.com



Continental Group Edmonton

Continental Electrical Motor Services Ltd.

MOTOR TORQUE CURRENT/SPEED ANALYSIS REPORT

CUSTOMER:	NEP/MAC Engineering	DATE:	2016 Oct 13
LOCATION:	CEMSN Shop	JOB NUMBER:	ES03383
SUBSTATION:	NA	EQUIPMENT ID:	NA

NAMEPLATE INFORMATION

MANUFACT.:	Toshiba	HP/KW:	2500 / 1865
MODEL/TYPE:	TIKE	RPM:	1182
STYLE NO.:	NA	VOLTS/PHASES	4160 / 3
SERIAL NO.:	060011007BH	FREQUENCY:	60
FLA:	331	FRAME:	500-1400
S.F.:	1	CODE LETTER:	F
RISE:	F	INS. CLASS:	H

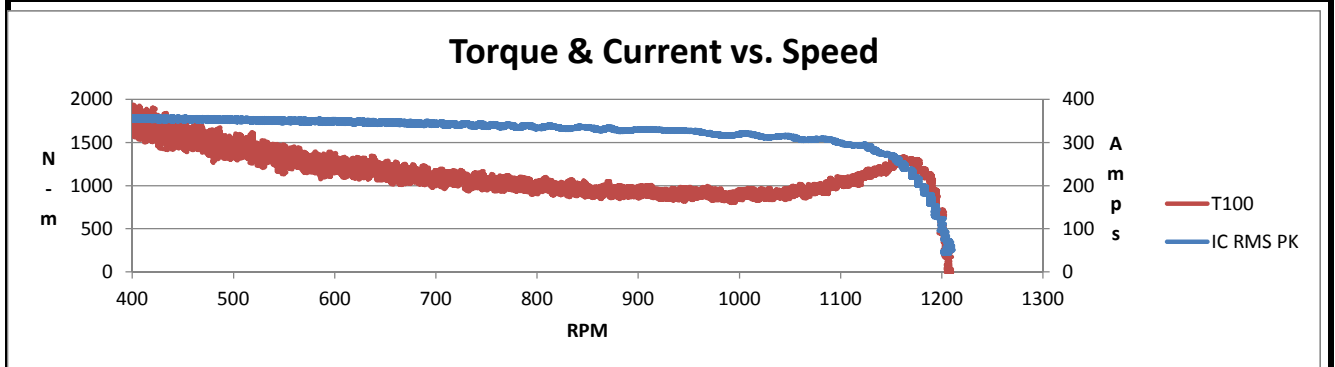
BASIC MOTOR PARAMETERS

Winding Res R_1	0.0000963 Ω	Winding Ind L_1	0.00904 H	Winding Imp X_{L1}	3 Ω
Ambient Temp T_a	18.6 $^{\circ}\text{C}$	Winding Temp T_c	20.2 $^{\circ}\text{C}$		
Full Ld Torque ψ_L	15068 N-m	*1 Des PU Tq ψ_U	9041 N-m	*1 Des BD Tq ψ_{BD}	26370 N-m
Motor Inertia J_M	206 Kgm^2	*1 Des Inertia Ld J_L	844 Kgm^2		

FIRST RUN

Volts V_{LL}	899 V	Current I_U	246 A	Speed ψ_n	1200 rpm
Avg VA S	382900 VA	Avg Watts P	77000 W	Avg Vars Q	375077.8719 Var
Avg Tq ψ_M	1011 N-m	Inertia J_M	206 Kgm^2		
Ambient Temp T_a	18.6 $^{\circ}\text{C}$	Wdg Temp Start T_c	20.2 $^{\circ}\text{C}$	Wdg Temp Pk T_H	21.2 $^{\circ}\text{C}$
Time Acc ψt_{acc}	s				

τ/n I/n Curves



COMMENTS

*1 NEMA MG1 Std.

INSPECTED BY:	TEST DEVICE(S):
 (PRINT NAME)	
 (SIGNATURE)	



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SUBSTATION:	NA	EQUIPMENT ID:	NA

NAMEPLATE INFORMATION

MANUFACT.:	Toshiba	HP/KW:	2500 / 1865
MODEL/TYPE:	TIKE	RPM:	1182
STYLE NO.:	NA	VOLTS/PHASES	4160 / 3
SERIAL NO.:	060011007BH	FREQUENCY:	60
FLA:	331	FRAME:	500-1400
S.F.:	1	CODE LETTER:	F
RISE:	F	INS. CLASS:	H

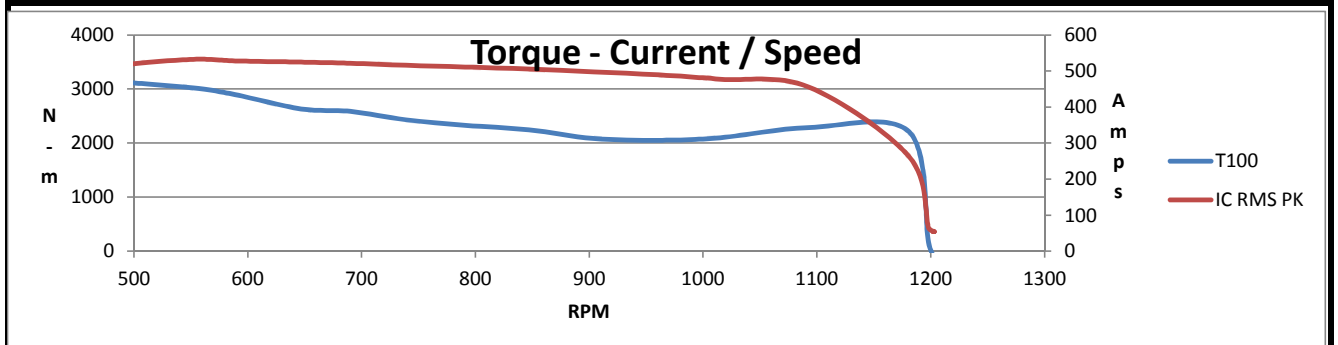
SECOND RUN

Volts V_{LL}	808 V	Current I_L	230 A	Speed ω_n	1200 rpm
Avg VA S	401000 VA	Avg Watts P	80300 W	Avg Vars Q	392878 Var
Avg Tq ψ_M	3400 N-m	Inertia J_M	204 Kg m^2		
Ambient Temp T_a	19.1 °C	Wdg Temp Start T_c	21.4 °C	Wdg Temp Pk T_H	23.1 °C
Time Acc ψt_{acc}	24.8 s				

SECOND RUN STEADY STATE

Volts V_{LL}	1050 V	Current I_L	30 A	Speed ω_n	0 rpm
Avg VA S	51500 VA	Avg Watts P	24500 W	Avg Vars Q	45299 Var
Avg Tq ψ_M	160 N-m	Inertia J_M	204 Kg m^2		
Ambient Temp T_a	21.2 °C	Wdg Temp Start T_c	27.8 °C	Wdg Temp Pk T_H	45.5 °C

τ/n / I/n Curves



COMMENTS

INSPECTED BY:	TEST DEVICE(S):
 (PRINT NAME)	
 (SIGNATURE)	



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MOTOR TORQUE CURRENT/SPEED ANALYSIS REPORT

CUSTOMER: NEP/MAC Engineering

LOCATION: CEMSN Shop

SUBSTATION: NA

DATE: 2016 Oct 13

JOB NUMBER: ES03383

EQUIPMENT ID: NA

NAMEPLATE INFORMATION

MANUFACT.: Toshiba

MODEL/TYPE: TIKE

STYLE NO.: NA

SERIAL NO.: 060011007BH

FLA: 331

S.F.: 1

RISE: F

HP/KW: 2500 / 1865

RPM: 1182

VOLTS/PHASES 4160 / 3

FREQUENCY: 60

FRAME: 500-1400

CODE LETTER: F

INS. CLASS: H

ACCELERATION FIRST RUN

Volts V_{LL}	899 V	Current I_L	246 A	Speed n	1200 rpm
Avg VA S	382900 VA	Avg Power P	77000 W	Avg Vars Q	375078 Var
Avg Tq ψ_M	6700 N.m	Avg Inertia J_M	206 Kg m^2		
Ambient Temp T_a	18.6 °C	Wdg Temp Start T_C	20.2 °C	Wdg Temp Pk T_H	21.2 °C
				Wdg Res R_{1H}	9.66781E-05 =

STEADY STATE FIRST RUN

Volts V_{LL}	899 V	Current I_L	107 A	Speed n	1200 rpm
Avg VA S	777000 VA	Avg Watts SS P_{fw}	91000 W	Avg Vars Q	771653 Var
Avg Tq ψ_M	760 N-m	Inertia J_M	206 Kg m^2	MG1 Des Inertia J_L	844 Kg m^2
Ambient Temp T_a	18.7 °C	Wdg Temp Start T_H	27.8 °C	Wdg Temp Pk T_{H1}	45.5 °C
				Wdg Res R_{1H1}	9.05667E-05 =

ACCELERATION TIME

Full Ld Tq ψ_{FL}	15068 N.m	Breakdown Tq ψ_{BD}	1236 N.m	Pull-up Tq ψ_{PU}	921 N.m
Frict Wind Tq ψ_{fw}	760 N.m	BD Tq @ Full Volts	26466 N-m	PU Tq @ Full Volts	19721 N-m
FW Tq @FV ψ_{fw}	16273 N-m	Accel Tq ψ_{acc}	3436 N.m		
		Accel Tq @ Full V	73582 N-m		
		Motor & Load Acc t_a	38 s		
		Accel t_a @FV	2 s		

COMMENTS

INSPECTED BY:

TEST DEVICE(S):

(PRINT NAME)

(SIGNATURE)

MOTOR TORQUE CURRENT/SPEED ANALYSIS REPORT

CUSTOMER:	NEP
LOCATION:	CEMSN Shop
SUBSTATION:	NA

DATE:	2016 Oct 13
JOB NUMBER:	ES03383
EQUIPMENT ID:	NA

NAMEPLATE INFORMATION

MANUFACT.:	IEM
MODEL/TYPE:	765621
STYLE NO.:	NA
SERIAL NO.:	8904001
FLA:	155
S.F.:	1.15
RISE:	B

HP/KW:	1250	/	932.5
RPM:	1191		
VOLTS/PHASES	4160	/	3
FREQUENCY:	60		
FRAME:	6808		
CODE LETTER:	C		
INS. CLASS:	F		

THERMAL CAPACITY DATA

Volts V_{LL}	4177 V	Current I_u	37 A	Speed μn	1200 rpm
Avg VA S	268000 VA	Avg Power P	95400 W	Avg Vars Q	250445 Var
Avg Tq u_M	800 N.m	Time to Stab sec	8400 s	Speed $\mu\%$	191 rad/s
Ambient Temp T_a	18.7 °C	Wdg Temp Start T_C	27.8 °C	Wdg Temp Pk T_H	45.5 °C
				Wdg Res R_{1H}	0.000287152 μ

THERMAL CAPACITY DATA 2

Inertia J _M	83 Kg ^m ²	MG1 Des Inertia J _L	480 Kg ^m ²	Design Ambient	40 °C
Motor & Load Acc t _a	34 s	Test Voltage	400 V	Insulation Class	155 °C
M&L Tq	3198 N-m	Rated Voltage	2400 V	Damage Temp	195 °C
M&L Tq FV	115119 N-m				
M&L Power @FV	21986134 W				

THERMAL CAPACITY CALCULATION

[illegible]

COMMENTS

INSPECTED BY:	TEST DEVICE(S):
(PRINT NAME) (SIGNATURE)	